

A Linear Programming Approach to Max-sum Problem: A Review

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Max-Sum Problem

$$\max_{\mathbf{x} \in X^T} \left[\sum_{t \in T} g_t(x_t) + \sum_{\{t, t'\} \in E} g_{tt'}(x_t, x_{t'}) \right]$$

e.g. the MAP problem on MRFs

Formulation of the Problem

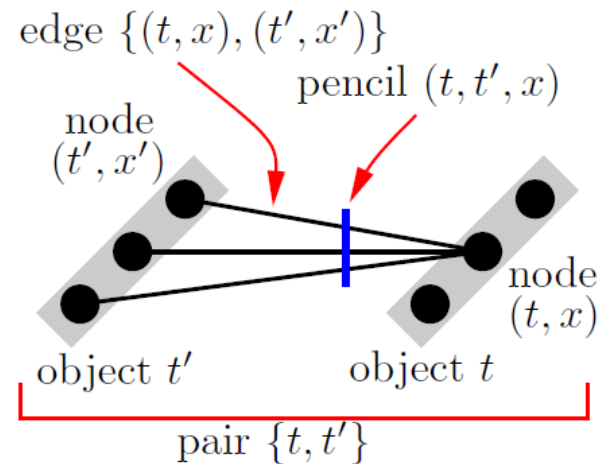
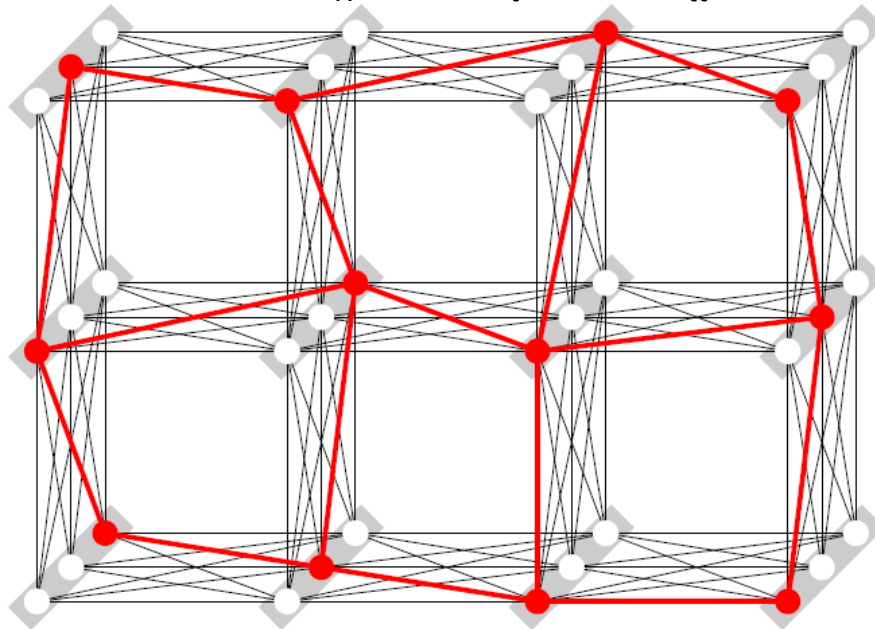
$$G = (T, E)$$

T is a set of objects, $x_t \in X$ is a labeling on t

$$E \subseteq \binom{T}{2}$$

$$G' = (T \times X, E_X)$$

$$g_t = (t, x) \quad g_{tt'} = \{(t, x), (t', x')\}$$



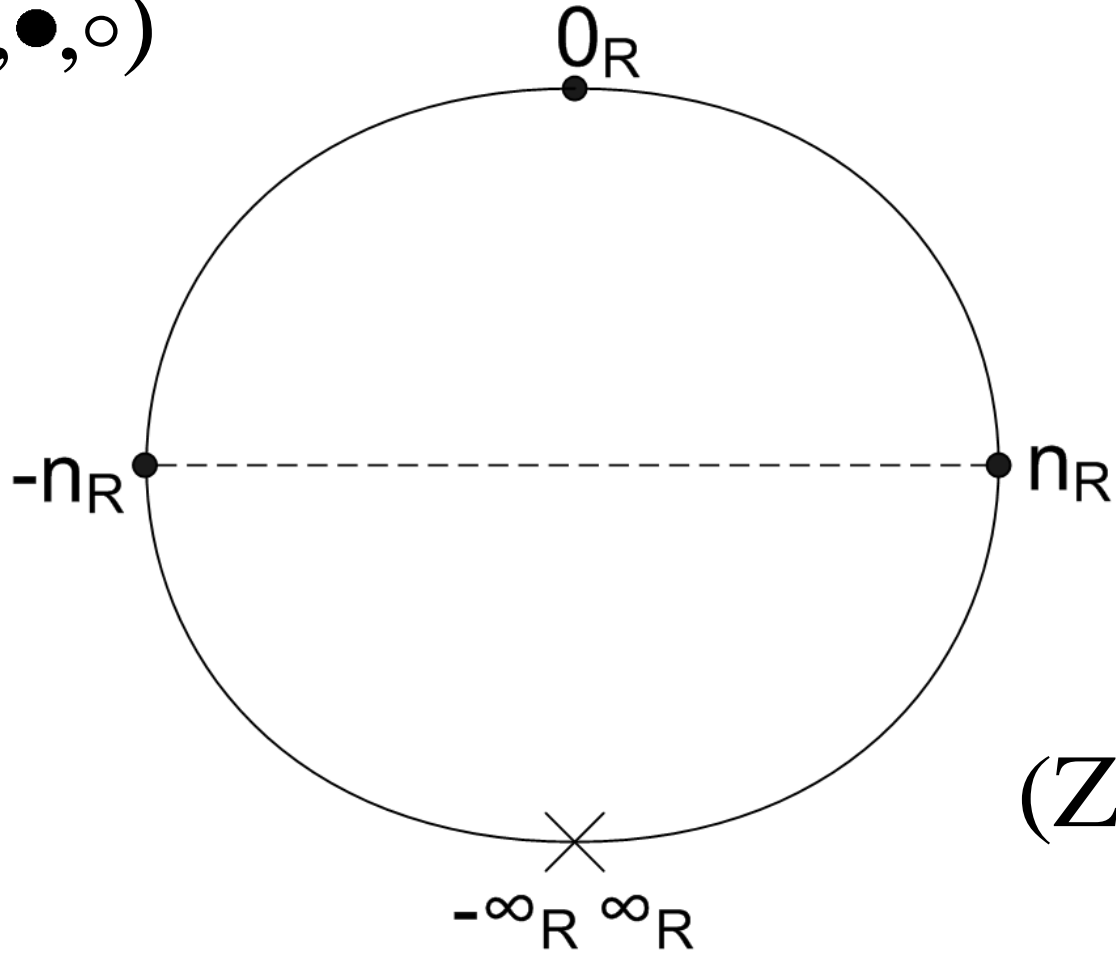
Commutative Semirings

$$\bigoplus_{\mathbf{x} \in X^{|T|}} \left[\bigotimes_t g_t(x_t) \otimes \bigotimes_{\{t,t'\}} g_{tt'}(x_t, x'_t) \right]$$

(S, \oplus, \otimes)	task
$(\{0, 1\}, \vee, \wedge)$	or-and problem, CSP
$([-\infty, \infty), \min, \max)$	min-max problem
$([-\infty, \infty), \max, +)$	max-sum problem
$([0, \infty), +, *)$	sum-product problem

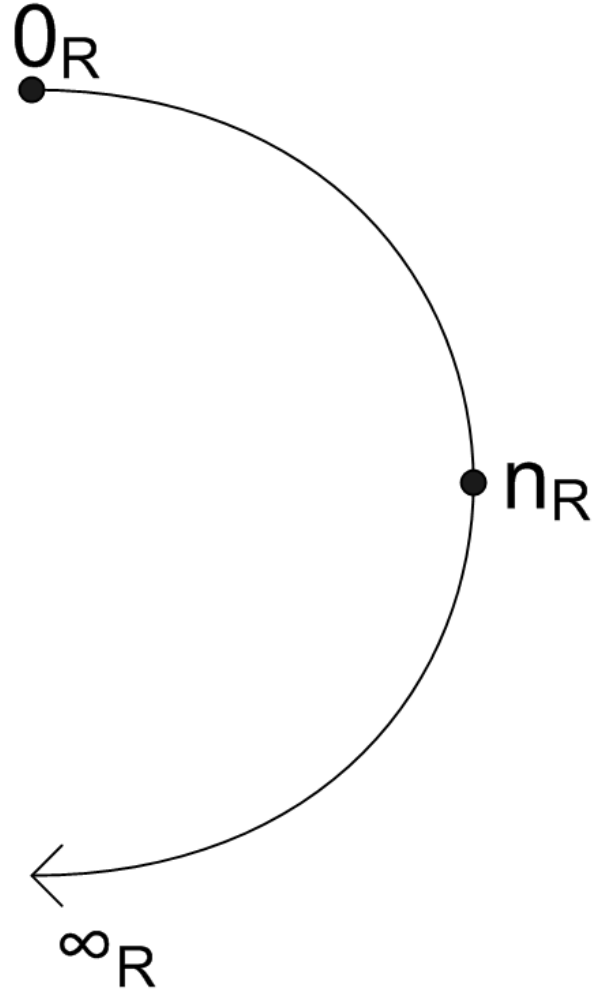
Rings

(S, \bullet, \circ)



$(Z, +, *)$

Semirings



Semirings

CSP

Denote a problem by (G, X, \bar{g}) – Graph, Domain, Constraints

Let $\bar{g}_t(\mathbf{x}), \bar{g}_{tt'}(\mathbf{x}, \mathbf{x}') = \{0, 1\}$ say if an assignment is allowed or forbidden

$$\bar{L}_{G, X}(\bar{\mathbf{g}}) = \left\{ \mathbf{x} \in X^T \mid \bigwedge_t \bar{g}_t(x_t) \wedge \bigwedge_{\{t, t'\}} \bar{g}_{tt'}(x_t, x_{t'}) = 1 \right\}$$

Arc consistency in CSP

$$\bar{g}_{tt'}(x, x') \in \{0, 1\}$$

$$\bigvee_{x'} \bar{g}_{tt'}(x, x') = \bar{g}_t(x), \quad \{t, t'\} \in E, x \in X$$

The **kernel** can be obtained by iteratively applying the following relations until no more 0 assignments are made (arc consistency algorithm)

$$\bar{g}_t(x) := \bar{g}_t(x) \wedge \bigvee_{x'} \bar{g}_{tt'}(x, x'),$$

$$\bar{g}_{tt'}(x, x') := \bar{g}_{tt'}(x, x') \wedge \bar{g}_t(x) \wedge \bar{g}_{t'}(x')$$

Semirings

Max-sum

Denote a problem by (G, X, g) – Graph, Assignments, Weights

$$F(\mathbf{x} \mid \mathbf{g}) = \sum_{t \in T} g_t(x_t) + \sum_{\{t, t'\} \in E} g_{tt'}(x_t, x_{t'})$$

$$L_{G, X}(\mathbf{g}) = \operatorname{argmax}_{\mathbf{x} \in X^T} F(\mathbf{x} \mid \mathbf{g})$$

Equivalent Transformations

Also known as ERs (Wainwright)

A problem is called equivalent if (G, X, g) and (G, X, g') produce the same problem, denoted as $g \sim g'$

The simplest such transformation adds a number $\phi_{tt'}(x)$ to $g_t(x)$ while removing from $g_{t'}(x, x')$

This formulation corresponds to *potentials* or *messages* from message passing

$$g_t^\varphi(x) = g_t(x) + \sum_{t' \in N_t} \varphi_{tt'}(x),$$

$$g_{tt'}^\varphi(x, x') = g_{tt'}(x, x') - \varphi_{tt'}(x) - \varphi_{t't}(x')$$

Schlesinger's Upper Bound

$$u_t = \max_x g_t(x), \quad u_{tt'} = \max_{x,x'} g_{tt'}(x, x')$$

$$U(\mathbf{g}) = \sum_t u_t + \sum_{\{t,t'\}} u_{tt'}$$

$$U^*(\mathbf{g}) = \min_{\varphi \in \mathbb{R}^P} \left[\sum_t \max_x g_t^\varphi(x) + \sum_{\{t,t'\}} \max_{x,x'} g_{tt'}^\varphi(x, x') \right]$$

Triviality

(t,x) is a maximal node if $g_t(x) = u_t$

$\{(t,x), (t',x')\}$ is a maximal edge if $g_{tt'}(x,x') = u_{tt'}$

$$\bar{g}_t(x) = [[g_t(x) = u_t]] \quad \bar{g}_{tt'}(x) = [[g_{tt'}(x,x') = u_{tt'}]]$$

A max-sum problem is **trivial** if a labeling can be formed of a subset of its maximal nodes and edges

Theorem 4. *Let C be a class of equivalent max-sum problems. Let C contain a trivial problem. Then, any problem in C is trivial if and only if its height is minimal in C .*

Triviality

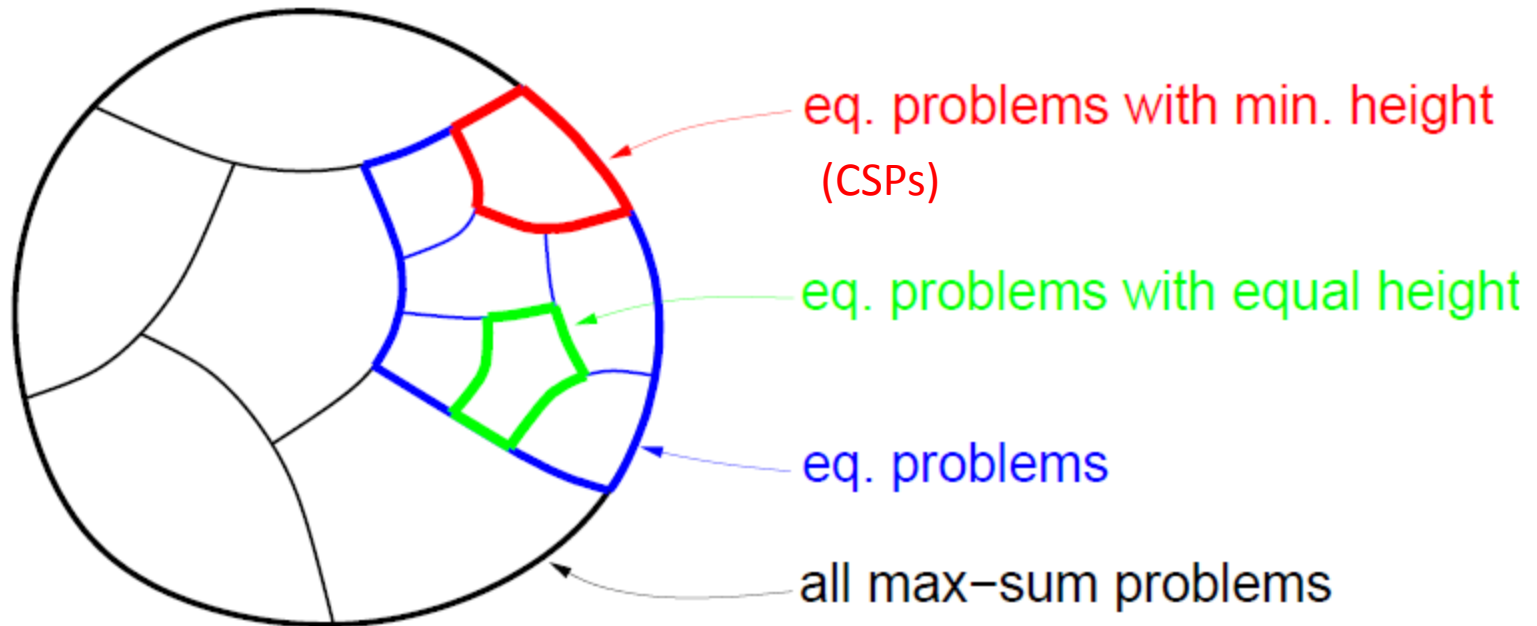
Theorem 4. *Let C be a class of equivalent max-sum problems. Let C contain a trivial problem. Then, any problem in C is trivial if and only if its height is minimal in C .*

1. minimize the problem height by equivalent transformations and
2. test the resulting problem for triviality.

Testing for triviality of a max-sum problem is correspondent to solving the CSP generated by its maximal nodes and edges

A CSP is a tight solution to all max-sum problems it can be equivalently transformed into

Equivalent Transformations



Linear Programming Relaxation

$$\sum_{x'} \alpha_{tt'}(x, x') = \alpha_t(x), \quad \{t, t'\} \in E, \quad x \in X,$$

$$\sum_x \alpha_t(x) = 1, \quad t \in T,$$

$$\alpha \geq \mathbf{0},$$

This gives the polytope $\Lambda_{G,X}$

which has a set of

optimal vertices given by $\Lambda_{G,X}(\mathbf{g}) = \operatorname{argmax}_{\alpha \in \Lambda_{G,X}} \langle \mathbf{g}, \alpha \rangle$

$$\langle \mathbf{g}, \alpha \rangle = \sum_t \sum_x \alpha_t(x) g_t(x) + \sum_{\{t,t'\}} \sum_{x,x'} \alpha_{tt'}(x, x') g_{tt'}(x, x')$$

Duality of the Relaxations

$$\langle \mathbf{g}, \boldsymbol{\alpha} \rangle \rightarrow \max_{\boldsymbol{\alpha}} \quad \sum_{t \in T} u_t + \sum_{\{t, t'\} \in E} u_{tt'} \rightarrow \min_{\boldsymbol{\varphi}, \mathbf{u}} \quad (11a)$$

$$\sum_{x' \in X} \alpha_{tt'}(x, x') = \alpha_t(x) \quad \varphi_{tt'}(x) \in \mathbb{R}, \quad \{t, t'\} \in E, x \in X \quad (11b)$$

$$\sum_{x \in X} \alpha_t(x) = 1 \quad u_t \in \mathbb{R}, \quad t \in T \quad (11c)$$

$$\sum_{x, x' \in X} \alpha_{tt'}(x, x') = 1 \quad u_{tt'} \in \mathbb{R}, \quad \{t, t'\} \in E \quad (11d)$$

$$\alpha_t(x) \geq 0 \quad u_t - \sum_{t' \in N_t} \varphi_{tt'}(x) \geq g_t(x), \quad t \in T, x \in X \quad (11e)$$

$$\alpha_{tt'}(x, x') \geq 0 \quad u_{tt'} + \varphi_{tt'}(x) + \varphi_{t't}(x') \geq g_{tt'}(x, x'), \quad \{t, t'\} \in E, x, x' \in X \quad (11f)$$

Theorem 5. *The height of (G, X, \mathbf{g}) is minimal of all its equivalents if and only if $(G, X, \bar{\mathbf{g}})$ is relaxed-satisfiable. If it is so, then $\Lambda_{G, X}(\mathbf{g}) = \bar{\Lambda}_{G, X}(\bar{\mathbf{g}})$.*

More theorems fall out

Theorem 6. *Let (G, X, \bar{g}^*) be the kernel of a CSP (G, X, \bar{g}) .
Then, $\bar{\Lambda}_{G,X}(\bar{g}) = \bar{\Lambda}_{G,X}(\bar{g}^*)$.*

Theorem 7. *A nonempty kernel of (G, X, \bar{g}) is necessary for its relaxed satisfiability and, hence, for minimal height of (G, X, \mathbf{g}) .*

Finding the kernel does not guarantee finding a solution for the minimal upper bound

Obvious by approach from CSPs

For problems of boolean variables $|X| = 2$
finding the kernel is necessary and sufficient
for finding the upper bound

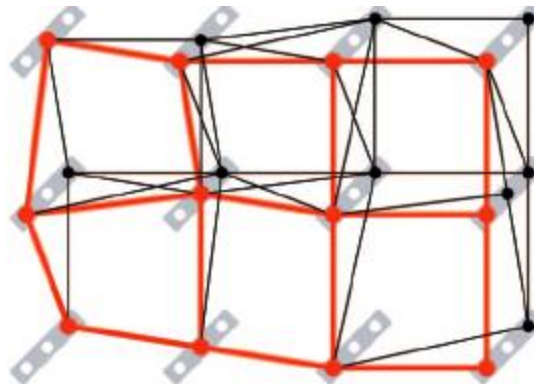
\bar{g} satisfiable \Rightarrow \bar{g} relaxed-satisfiable \Rightarrow kernel of \bar{g} nonempty
 \mathbf{g} trivial \Rightarrow height of \mathbf{g} minimal

(Super) Submodularity

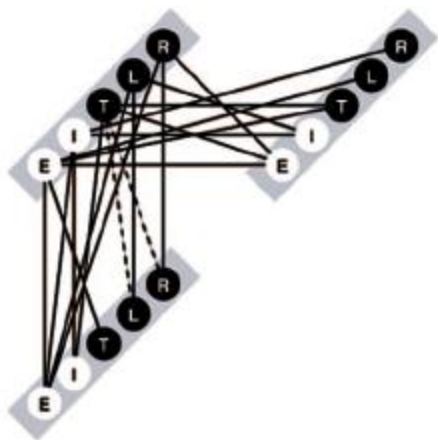
Known that the (super) submodularity property produces max-sum problems with tractable solutions by conversion to max-flow/min-cut problems

Has been suggested that supermodularity is the discrete counterpart of convexity. Lots of work shows that the LP relaxation for a supermodular max-sum problem is tight

Supermodular max-sum problems will always form a **lattice CSP** with a tractable solution



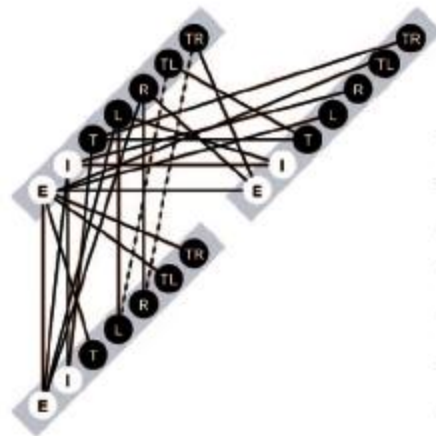
An application (not just theory!)



(a)



(b)



(a)



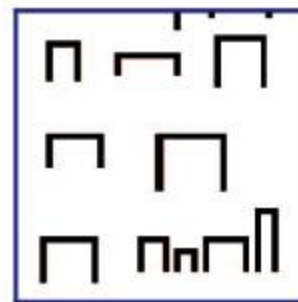
(b)



(c)

(d)

(e)



(c)