

Rooted Cycle Bases

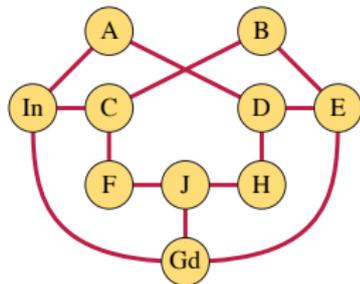
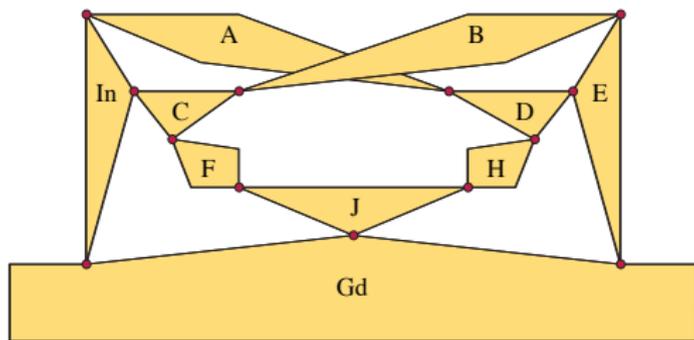
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Linkages

Systems of rigid bodies connected by hinges

Often with designated ground body (fixed in place)
and input body (where force input causes system to move)

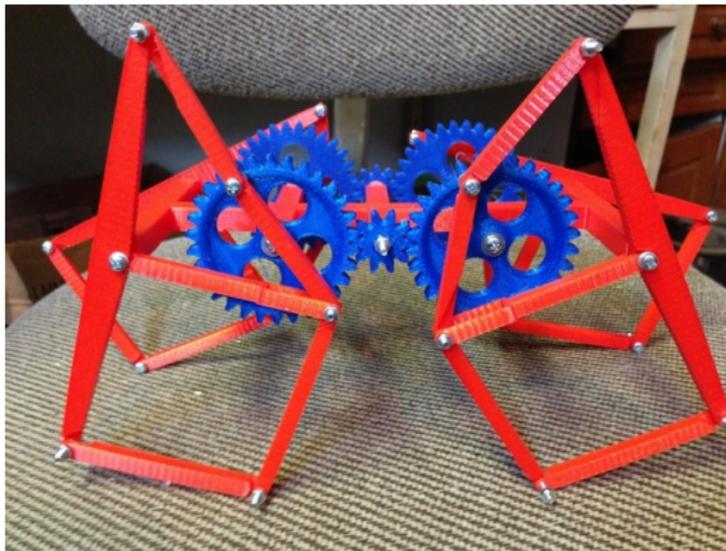


Connectivity may be described by a graph
with vertices = bodies and edges = hinges

Simplifying assumptions: system lies in \mathbb{R}^2 (crossings allowed);
input is attached to ground (so its motion is purely rotational)

Complex linkages can have complex motions

CC-BY-SA image of Amanda Ghassaei Walker by diehart, <http://www.thingiverse.com/thing:264726>



Applications include walking robots, fold-away sofas/beds, vehicle suspensions, low-clearance doors, therapeutic exoskeletons, . . .

Our piece of a larger puzzle

Goal:

design linkage that achieves
some desired motion

Sub-goal:

Analyze motion of a linkage

Sub-sub-goal:

Set up independent equations
for the motion of a linkage

Combinatorial abstraction:

Find independent input-ground
paths in the graph of a linkage



CC-BY image "Close up of Hand Cut Jigsaw Puzzle" by Charles Hamm on Wikimedia commons

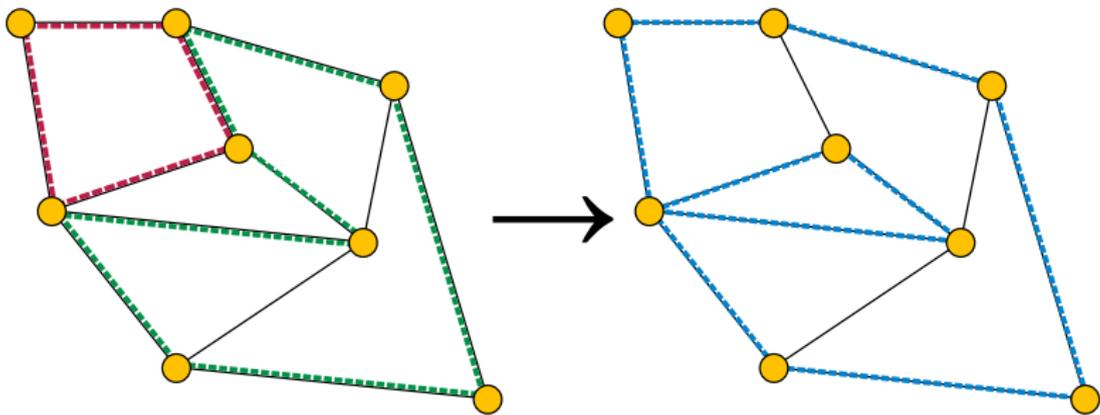
Independence of cycles in graphs

Cycle space: a vector space over \mathbb{Z}_2

Elements = sets of edges with even degree at all vertices

Vector sum = symmetric difference of edge sets

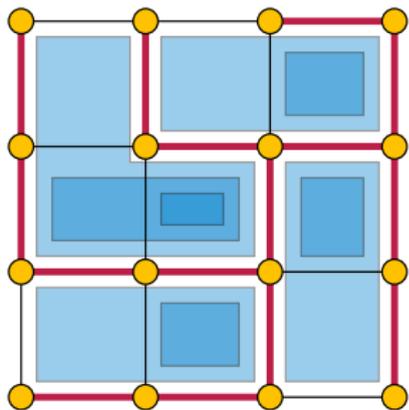
Scalar product = trivial



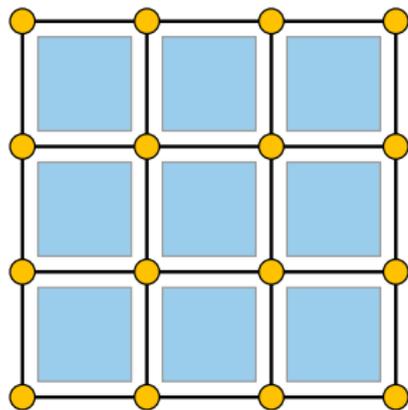
Based on CC-BY-SA image "Cycle space addition" by Kilom691 on Wikimedia commons

Cycle bases

Cycle basis = basis of the cycle space =
maximal independent set of cycles



Fundamental cycle basis:
cycles are spanning tree
paths + one edge



In planar graphs,
bounded faces form
a cycle basis

Greed is good



Avarice, from *The Dunois Hours*, France, ca. 1440-1450. Public domain image "The Dunois Hours Avarice" on Wikimedia commons.

Independence in a vector space forms a matroid \Rightarrow minimum weight cycle bases can be found by a greedy algorithm

For each candidate cycle, sorted by weight, test if independent and, if it is, include in basis

The difficult part: finding a small set of candidate cycles

When all weights positive, possible in polynomial time

What kind of cycle basis do we need?

Paths from linkage input to ground \Leftrightarrow cycles that all pass through a “root edge” incident to input and ground

Rooted graph: undirected graph + one chosen root edge

Rooted cycle basis: all cycles in the basis include the root edge

Higher cycle length gives more complex equations to solve, so we want a minimum weight rooted cycle basis



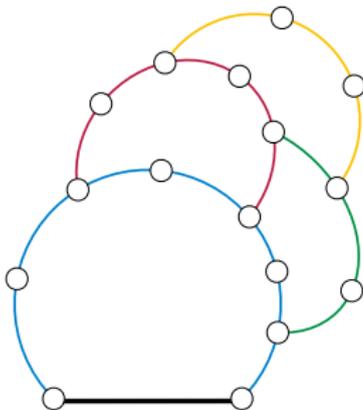
Plate to: H. J. Ruprecht, wand-atlas, ed. 3, Dresden, c. 1850, no. 15. Public domain image “A plant root cut to show growth rings, wood cells in longitu Wellcome V0044550” on Wikimedia commons.

Warm-up result

Rooted cycle basis exists if and only if graph has one non-trivial 2-vertex-connected component and it contains the root edge

Proof uses ear decomposition:

- ▶ Sequence of simple paths
- ▶ First path = root edge
- ▶ Endpoints of remaining paths lie on earlier paths
- ▶ Interior vertices of each path are disjoint from earlier paths



Proof idea: Extend each ear to rooted cycle through previous ears

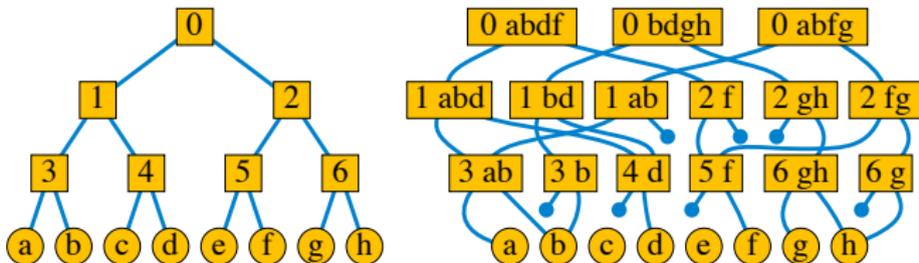
Breaking ties

Correctness proof is only valid when all cycle lengths are distinct

Small random perturbation works but requires randomness

Perturbation by small powers of two works
but requires too many bits of numerical precision

Data structure for simulating power-of-two perturbation
incurs only logarithmic slowdown



Conclusions

New type of cycle basis

Motivated by applications in linkage analysis

With a polynomial time optimization algorithm

Also useful for other applications?